# **MOD.580 SERVICE MANUAL**

For checking each unit (any failure and its troubleshooting) using the Design Controller PE1 and for replacing and adjusting each unit using the PE1 and an analog-type tester.

#### Foreword

Without locating where a trouble occurred, no repair is possible. This electronic knitting machine may cause a mechanical trouble or electrical trouble.

For a mechanical trouble, how to adjust the arm unit other than a breakdown or wear is described here.

For an electrical trouble, it is hard to locate an exact trouble spot without using various instruments and electrical knowledge.

In this basic and intermediate manual, how to detect a faulty unit, replace it and adjust and check the substituted unit is described. Therefore, with the PEl and tester, anybody can repair, replace and adjust easily.

This Can be used for the SK-840/860/890 [Note by shop owner]

\* Contents \* in after completing each item.

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1. Checking the Knitting Machine and PE1

\* Be sure to turn off the Power Switch after completing each item.

1-1 How to Check the Knitting Machine (Any Trouble)





#### 1-2 Checking the PE1 Unit [Self-check Function]

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#### 2. Curl Cord Check

\* With the self-check function of PEl Unit, whether the Curl Cord connecting the Knitting Machine and the Carriage has any disconnection or not is checked.



4. Carriage Unit Check [CRG.CHECK]

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To be continued.



- 5. How to Replace the CR (Card Reader) Unit
  - \* Remove the Pattern Card and turn off the Power Switch.



- 6. How to Adjust the CR Unit (Using the PE1 Unit and Analog-type Tester)
  - \* The level of each sensor for the CR Unit replacement has been tentatively adjusted, but be sure to check again before replacement.

6-1 How to Adjust the PCP (pattern Clock Pulse) Output Voltage



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### 6-2 How to Check and Adjust the Card Holder and Pattern Card



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6-4 How to Check and Adjust the PSD (Preset Data) Output Voltage





6-5 How to Check the PCP (Pattern Clock Pulse) Timing

- 7. How to Adjust Each Sensor of the Carriage
  - \* Each sensor of the Carriage for replacement has been tentatively adjusted. However, as the CCP Output Voltage and Selection Timing are varied depending on a Needle Bed Clock Plate, be sure to adjust again whenever the Carriage is replaced.

#### 7-1 How to Remove the Carriage Cover





7-2 How to Adjust the CCP (Carriage Clock Pulse) Output Voltage

to be continued.



7-3 How to Adjust the CCP Needle Selection Timing



To be continued.



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1) When the adjustment is correct, normal KSL display is 4 within +4 dots and the ND1 display within +2 dots for the CCP display's (A) point. For the right side, the ND1 display is given a priority as the KSL and ND1 sensors are integrated. (Note) The display value varies depending on a speed of the Carriage movement. (A) 0 Ð - CCP +4 KSL NA1 (+):(-):Loosen the one screw (a) fixing Loosen the one screw (a) fixing the KSL and ND1 holder (right) the KSL and ND1 holder (right) and move slightly to the left. and move slightly to the right. KSL/ND1  $\square$ 1 Holder 0 -5 3 3 Screw (a) \* After checking output of each right sensor, check each of the left sensors. 5 1) Shift the Carriage to the right side. 2) Press the key to delete the display. = 3) Move the Carriage slowly and return to the right side (starting position) when the dial reaches the Point Cam. 4) The PEl buzzer rings and output of each sensor is shown in the display section. 5) When a display is shown, pressing the key each time deletes the display. Point Cam of urfa 000 (A)CCP (B)KSL 137 TO Dial (Note) The CCP display in the PE1 display section is shown 1-1.4 times larger in its H (3.3+0.2V) value than in L when the CCP level has been properly adjusted. To be continued

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8. Correct Positions of the Arm, Needle Bed and Latch Needle



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When the Fabric Presser edge and the Latch Needle are in contact: 6 1) Remove the Arm from the Carriage. 2) Turn the Arm upside down and press it downward gently with your palm. If pressed too forcibly, the Arm may bend too much, applying too much force. Adjust gently so as to apply minimum pressure. 3) After adjusting the degree of contact between the Fabric Presser's left and right edge and the underside of the Latch Needle, adjust the gap between the Latch Needle and Yarn Feeder of the pointer right and left inside the Fabric Presser. 4) Move the Carriage so that the Latch Needle is positioned at the center of the Yarn Feeder. Yarn Fabric Feeder Presser 5) It is proper if the gap between the latch of 4th Latch Needle from the Yarn Feeder center and the Yarn Feeder is 0.1~0.3 within 0.1 - 0.3 m/m. \* Use a thickness gauge or a thin paper sheet to measure the appropriate gap. 6) When the gap is more than 0.3m/m, lift the Fabric Presser upward as in the above description. Latch 7) When the latch of the Latch Needle is in Projection contact with the Yarn Feeder, without a gap, adjust as in the following. When the Fabric Presser's edge is not slightly in contact with the Latch 7 Needle: 1) The Carriage with its Arm have to be shifted to the Needle Bed end of the Fabric Presser which has to be adjusted. 2) Hold the Fabric Presser end and bend the edge. 1010111111111 mill Fabric Presser - 22 -

#### 8-2 PS Adjustment



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When the gap is not in the range 0.3 -1.0 m/m, remove the Arm from the Carriage and loosen the two screws (a) fixing the Yarn Feeder. Install the Arm to the Carriage and insert the thickness gauge or scale for adjustment.
Thickness Gauge
Thickness Gauge
2 Screws

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Deviation of the DIN output level right & left +2 dote difference within +2 dots



The CR Sensor stays at right and

Check to see if the CR Sensor contacts the out of not. if the CR Sensor touches the mirror, move backward the CR Senso as much as they are not contact each other.

3) Adjust the DIN output level to 16+2 Dots (320+40mV) by turning the potentiometer with point V2.5 nath and the si equip of the fill of has been brought near to the CR Sensor, replace the mirror with one wan

c) Check to see if the mirror contacts the CR Sensor or not. If the mirror touches the Sensor, move backward the CR Unit as much as they are not contact each other, but should stay as close as possible.

#### 6-6 Adjusting Forward-Backward positioning of the CR Sensor

 Mount the CR Unit at the same position where it was marking-off before removing, and secure with one PW Pan Head Screw and other three screws are temporarily fastened.



2) Adjust the deviation of the output voltage to the permissible range, <u>+2</u> dots, by patting the position A or B with a screwdriver. Then fasten the four screws securely.



The CR Sensor stays at right end

Note:

Check to see if the CR Sensor contacts the mirror or not. if the CR Sensor touches the mirror, move backward the CR Sensor as much as they are not contact each other.

3) Adjust the DIN output level to 16+2 Dots (320+40mV) by turning the potentiometer (VR1).

6-7 Adusting the PSD Output Voltage

PSD level is produced by the mirror, positioned at the front of the CR Unit, when a light is reflected on the mirror and sensed by the CR Sensor.

1) If the PSD level is less than 2.5V, check to see if the mirror is dirty, and if so, wipe it clean with an alcohol damped cloth or using the sensor cleaner.



(Fig.3-26)

2) If the PSD output voltage is still less than 2.5V after the mirror has been cleaned, bring the mirror near to the CR Sensor by bending it as illustrated.



(Fig.3-27)

- 3) If the PSD output voltage is still less than 2.5V after the mirror has been brought near to the CR Sensor, replace the mirror with new one.
- 4) Check to see if the mirror contacts the CR Sensor or not. If the mirror touches the Sensor, move backward the CR Unit as much as they are not contact each other, but should stay as close as possible.

## 6-8 Adjusting the PCP Timing

- 1) Loosen two binding head screws(2.6x4) fixing the PCP interrupter.
- 2) Turn the binding head screw(3xl4) at the left end of the interrupter plate, and adjust the reference level to come to the center of each peak of the DIN signal.



Check to see if the CR Sensor contacts th(Compare) or not. If the CR Sensor touches the mirror, move backward the CR Sensor as much as they are not contact each other.

() If the PSD output voltage is still less than 2.5V aftering wireful that (c has been brought near to the CR Sensor, replace the mirror with

> ) Check to see if the mirror contacts the CR Sensor or not. If the mirror touches the Sensor, move backward the CR Unit as much as they are not contact each other, but should stay as close as possible.

CR UNIT



Round

1.ND1

2.KSL

3.DOE 4.CCF

5.HOK 6.16V 7. 5V 8.GND

- This unit consists of CR Sensor Unit, Pulse Motor Unit, Card Holder, CR Pointer (Mirror), etc. and the CR Sensor Unit is incorporated with \* DIN Sensor, PCP Sensor and Scan Solenoid needed to read out the patterns.
  - (a) DIN Sensor (DIN Output)
  - It is a sensor to read out Card Patterns. the DIN Output value is obtained from a value with the infrared ray reflected on the card. (b) PCP Sensor (PCP Output)
  - It is a timing signal to read out the DIN signal. The PCP Output signal is obtained from a value with the infrared ray passing through the PCP Clock Plate.
  - (c) Mirror (PSD Signal) It is provided to judge the end of a pattern. To distinguish from the DIN Output, this PSD Signal is obtained from a higher reflectance of the mirror reflected from the DIN Sensor.

#### MOD. 580 ELECTRICAL FUNCTION OF EACH UNIT

	SYMBOL	DESCRIPTION	FUNCTION	Carri
	DIN	Data In	Signal generated by the patterns on the Pattern Card.	Clock
C R UNIT	PCP PSD LMR	Pattern Clock Pulse Preset Data Linear Motor Right	Set the timing to read the pattern. Detects the Pattern Width. Move the CR sensor from left to right. Activated when the Inspection Key is pushed on or off,and when the Carriage passes the second Point Cam.	Interi
	L M L PM1-PM4	Linear Motor Left Pulse Motor	Move the CR Sensor from right to left. Governs the turning direction of the Pulse Motor.	
CARRIAGE	CCP KSL	Carriage Clock Pulse Point Cam	Represents number of needles. Detects the pattern knitting width. (It feeds the card one step when KSL passes the first Point Cam and the CR Sensor scans	
UNIT	N D 1 H O K -D O B	Needle 1 Direction Data Out Buffer	when passing the last Point Cam.) Sets the position of the pattern. Detects the proceeding direction of Carriage. Output of needle selection signal.	

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